

## Gauge Theories – First Set of Exercises

### 1 Free actions

Consider the following Lagrangians,

$$\mathcal{L}_{qed} = -\frac{1}{4}F_{\mu\nu}F^{\mu\nu} + \bar{\psi}(i\gamma^\mu\partial_\mu - M)\psi - eQA_\mu\bar{\psi}\gamma^\mu\psi, \quad (1)$$

$$\mathcal{L}_s = \frac{1}{2}\partial_\mu\phi\partial^\mu\phi - V(\phi), \quad (2)$$

$$\mathcal{L}_{cs} = \partial_\mu\phi_a^\dagger\partial^\mu\phi_b\delta^{ab} - V(\phi^a). \quad (3)$$

- Justify the sign and normalisation of the kinetic terms. What determines the sign of the potential term?
- Show that  $\mathcal{L}_{qed}$  is gauge invariant.
- Compute the equations of motion from requiring that the functional derivative of the respective actions,

$$\frac{\delta}{\delta\psi_l(x)}I(\psi_l) = 0, \quad I(\psi_l) = \int d^4x \mathcal{L}(\psi_l, \partial_\mu\psi_l), \quad (4)$$

vanishes. It is OK to compute this for a generic Lagrangian and then insert the explicit form of the Lagrangians.

- Compute the canonical momenta.

### 2 Non-abelian field strength tensor

Compute the field strength tensor  $F_{\mu\nu}^a$  from the commutator of covariant derivatives acting on a field  $\psi_l$ ,

$$([D_\mu, D_\nu]\psi)_l = -iF_{\mu\nu}^a(t_a)_l^m\psi_m. \quad (5)$$

Use the gauge transformations of the gauge potential,

$$\delta A_\mu^a = \partial_\mu\epsilon^a + C_{cb}^a\epsilon^b A_\mu^c, \quad (6)$$

to obtain the transformation behavior of the field strength tensor  $\delta F_{\mu\nu}^a$ .

### 3 Group properties

Given are the Lie-algebra generators  $t_a$  of  $SU(3)$  in the form of the Gell-Mann matrices  $\lambda_a$ ,

$$t_a = \frac{1}{2}\lambda_a, \quad (7)$$

$$\lambda_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \lambda_2 = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \lambda_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad (8)$$

$$\lambda_4 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad \lambda_5 = \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix}, \quad \lambda_6 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \quad (9)$$

$$\lambda_7 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix}, \quad \lambda_8 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}. \quad (10)$$

(a) Compute the structure constants  $C_{bc}^a$  from the commutators,

$$[t_a, t_b] = iC_{ab}^c t_c. \quad (11)$$

Feel free to employ a computer algebra system (e.g. FORM, Maple, Mathematica, etc) for this task.

(b) Write out the Jacobi identity in terms of the structure constants. Show that the adjoint generators  $(t_i^A)_b^a$ ,

$$(t_i^A)_b^a = -iC_{ib}^a, \quad (12)$$

fulfill the commutator relation of the Lie algebra.

(c) Compute the functions  $C_A$ ,  $C_F$ ,  $T_A$  and  $T_F$ .

### 4 The Haar Measure for $SU(2)$

Compute the Haar measure of the group  $SU(2)$  with the following instructions. The group is conveniently parametrized using the three angles  $\theta, \phi$  and  $\psi$  and Lie algebra generators proportional to the Pauli matrices,

$$\alpha^a = \theta \{ \cos(\psi) \sin(\phi), \sin(\psi) \sin(\phi), \cos(\phi) \}, \quad (13)$$

$$\tau_1 = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \tau_2 = \frac{1}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \tau_3 = \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad (14)$$

With this, any element of the group  $g$  can be expressed as:

$$\begin{aligned} g(\theta, \phi, \psi) &= \exp(i\alpha^a \tau_a) \\ &= \begin{pmatrix} \cos(\frac{\theta}{2}) + i \sin(\frac{\theta}{2}) \cos(\phi) & i \sin(\frac{\theta}{2}) \sin(\phi) \exp(-i\psi) \\ i \sin(\frac{\theta}{2}) \sin(\phi) \exp(i\psi) & \cos(\frac{\theta}{2}) - i \sin(\frac{\theta}{2}) \cos(\phi) \end{pmatrix}, \end{aligned} \quad (15)$$

with  $0 \leq \theta \leq 2\pi$ ,  $0 \leq \phi < \pi$  and  $0 \leq \psi \leq 2\pi$ .

(a) Verify the relation,

$$\text{Tr}(\tau_a \tau_b) = T_F \delta_{ab}, \quad T_F = \frac{1}{2}. \quad (16)$$

- (b) Compute the tangent vectors at the unit point corresponding to the directions  $\theta, \phi$  and  $\psi$ . Give the generators  $t_\theta, t_\psi$  and  $t_\phi$ .
- (c) The tangent vectors at a generic point of the group are translated back to the unit point using,

$$g^{-1} \frac{\partial}{\partial x^a} g = \sum i t_a M^{ab}, \quad x^a = \{\theta, \psi, \phi\}, \quad (17)$$

defining the matrix  $M(\theta, \psi, \phi)$ .

- (d) Compute the measure,

$$d\mu(\theta, \psi, \phi) = \frac{1}{V} \det(M) d\theta d\psi d\phi. \quad (18)$$